

# Probability Review I

# Probability Review

- Events and Event spaces
- Random variables
- Joint probability distributions
  - Marginalization, conditioning, chain rule, Bayes Rule, law of total probability, etc.
- Structural properties
  - Independence, conditional independence
- Mean and Variance
- The big picture
- Examples

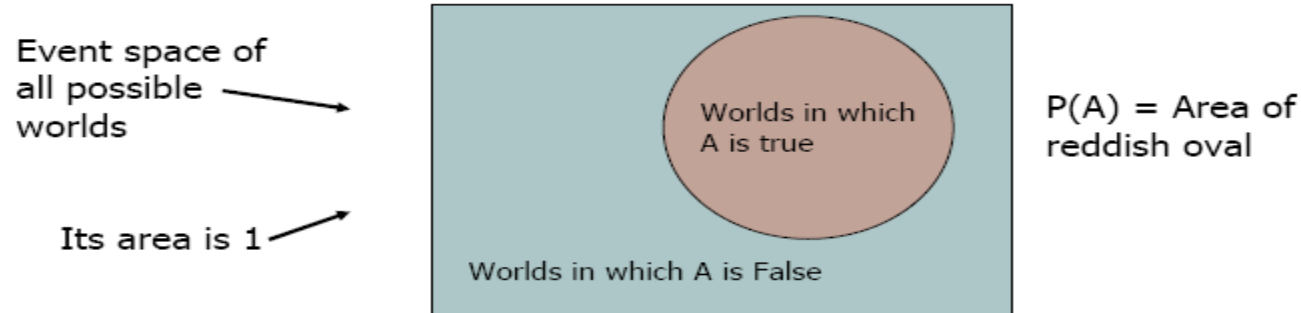
# Sample space and Events

- $\Omega$  : Sample Space, result of an experiment
  - If you toss a coin twice  $\Omega = \{HH, HT, TH, TT\}$
- Event: a subset of  $\Omega$ 
  - First toss is head =  $\{HH, HT\}$
- $S$ : event space, a set of events:
  - Closed under finite union and complements
    - Entails other binary operation: union, diff, etc.
  - Contains the empty event and  $\Omega$

# Probability Measure

- Defined over  $(\Omega, S)$  s.t.
  - $P(\alpha) \geq 0$  for all  $\alpha$  in  $S$
  - $P(\Omega) = 1$
  - If  $\alpha, \beta$  are disjoint, then
    - $P(\alpha \cup \beta) = p(\alpha) + p(\beta)$
- We can deduce other axioms from the above ones
  - Ex:  $P(\alpha \cup \beta)$  for non-disjoint event
$$P(\alpha \cup \beta) = p(\alpha) + p(\beta) - p(\alpha \cap \beta)$$

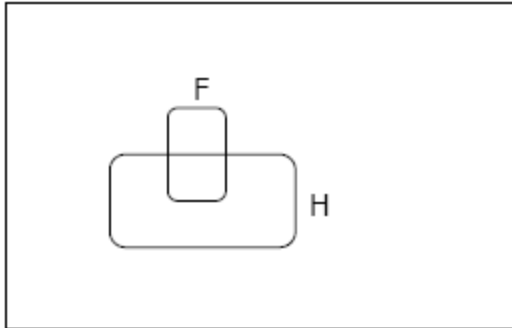
# Visualization



- We can go on and define conditional probability, using the above visualization

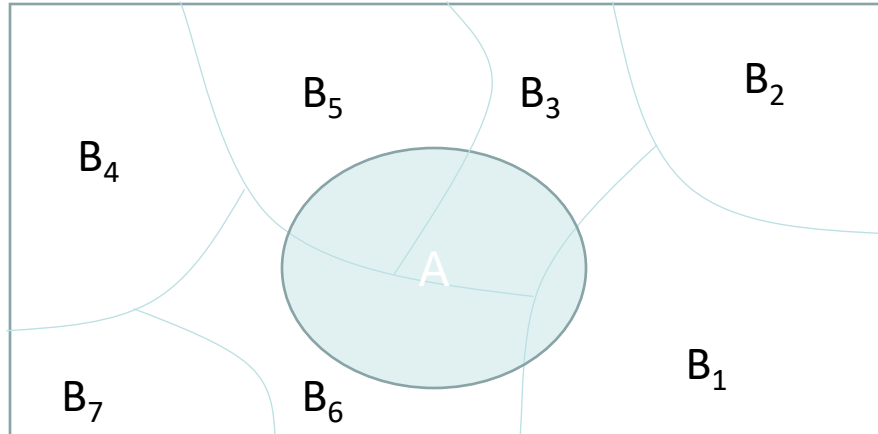
# Conditional Probability

$P(F | H)$  = Fraction of worlds in which  $H$  is true that also have  $F$  true



$$p(f | h) = \frac{p(F \cap H)}{p(H)}$$

# Rule of total probability



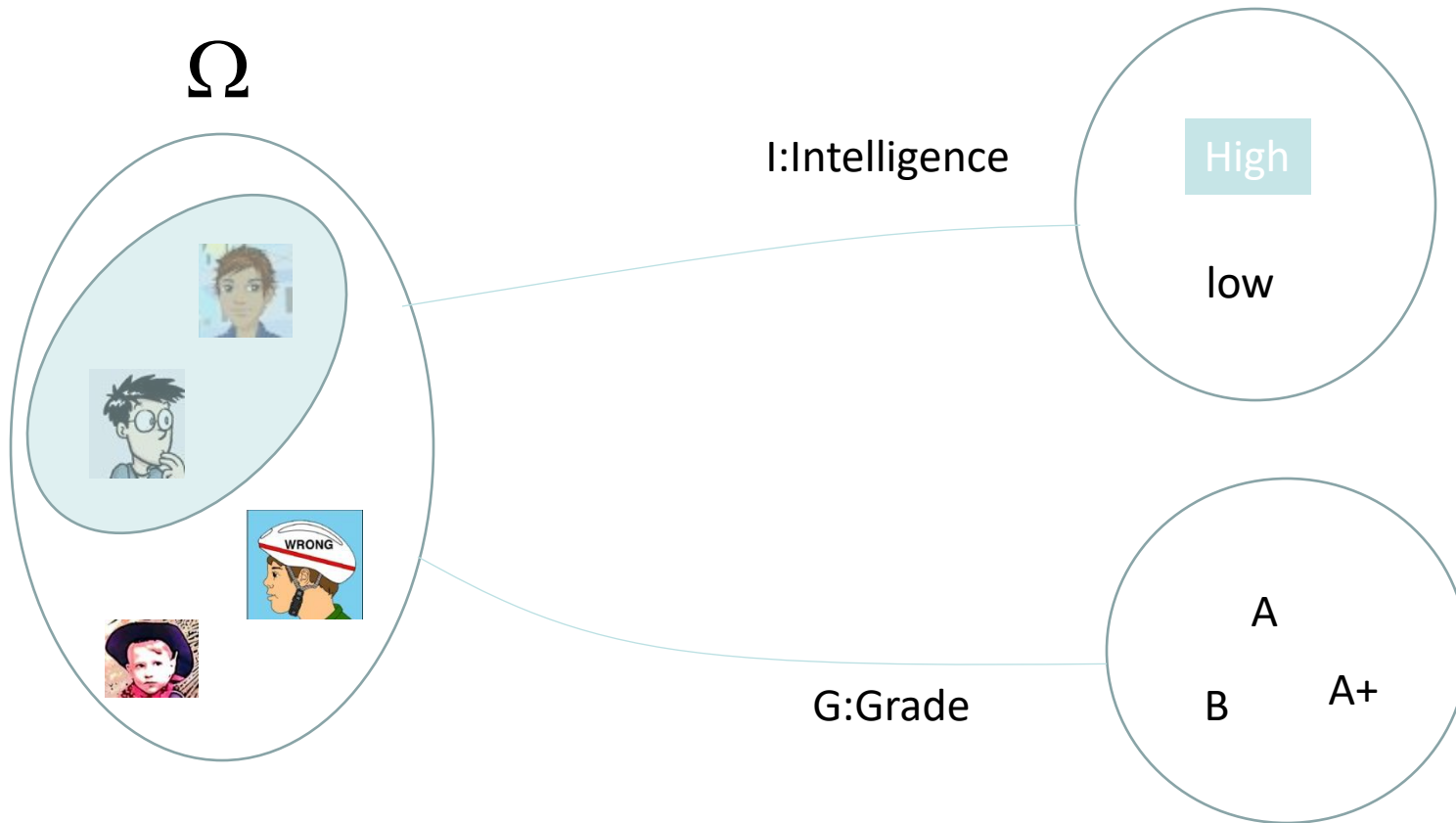
$$p(A) = \sum P(B_i)P(A | B_i)$$

# From Events to Random Variable

- Almost all the semester we will be dealing with RV
- Concise way of specifying attributes of outcomes
- Modeling students (Grade and Intelligence):
  - $\Omega =$  all possible students
  - What are events
    - Grade\_A = all students with grade A
    - Grade\_B = all students with grade B
    - Intelligence\_High = ... with high intelligence
  - Very cumbersome
  - We need “functions” that maps from  $\Omega$  to an attribute space.
  - $P(G = A) = P(\{\text{student} \in \Omega : G(\text{student}) = A\})$



# Random Variables



$$P(I = \text{high}) = P(\{\text{all students whose intelligence is high}\})$$

# Discrete Random Variables

- Random variables (RVs) which may take on only a **countable** number of **distinct** values
  - E.g. the total number of tails  $X$  you get if you flip 100 coins
- $X$  is a RV with arity  $k$  if it can take on exactly one value out of  $\{x_1, \dots, x_k\}$ 
  - E.g. the possible values that  $X$  can take on are 0, 1, 2, ..., 100

# Probability of Discrete RV

- Probability mass function (pmf):  $P(X = x_i)$
- Easy facts about pmf
  - $\sum_i P(X = x_i) = 1$
  - $P(X = x_i \cap X = x_j) = 0$  if  $i \neq j$
  - $P(X = x_i \cup X = x_j) = P(X = x_i) + P(X = x_j)$  if  $i \neq j$
  - $P(X = x_1 \cup X = x_2 \cup \dots \cup X = x_k) = 1$

# Common Distributions

- Uniform  $X \sim U[1, \dots, N]$ 
  - $X$  takes values  $1, 2, \dots, N$
  - $P(X = i) = 1/N$
  - E.g. picking balls of different colors from a box
- Binomial  $X \sim \text{Bin}(n, p)$ 
  - $X$  takes values  $0, 1, \dots, n$
  - $p(X = i) = \binom{n}{i} p^i (1-p)^{n-i}$
  - E.g. coin flips

# Continuous Random Variables

- Probability density function (pdf) instead of probability mass function (pmf)
- A pdf is any function  $f(x)$  that describes the probability density in terms of the input variable  $x$ .

# Probability of Continuous RV

- Properties of pdf
  - $f(x) \geq 0, \forall x$
  - $\int_{-\infty}^{+\infty} f(x) = 1$
- Actual probability can be obtained by taking the integral of pdf
  - E.g. the probability of  $X$  being between 0 and 1 is

$$P(0 \leq X \leq 1) = \int_0^1 f(x) dx$$

# Cumulative Distribution Function

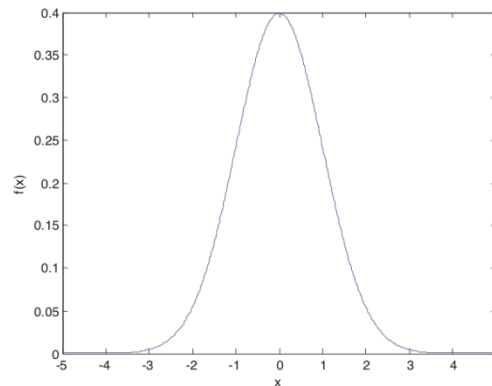
- $F_X(v) = P(X \leq v)$
- Discrete RVs
  - $F_X(v) = \sum_{v_i} P(X = v_i)$
- Continuous RVs
  - $F_X(v) = \int_{-\infty}^v f(x) dx$
  - $\frac{d}{dx} F_X(x) = f(x)$

# Common Distributions

- Normal  $X \sim N(\mu, \sigma^2)$

- $$f(x) = \frac{1}{\sigma\sqrt{2\pi}} \exp\left(-\frac{(x - \mu)^2}{2\sigma^2}\right)$$

- E.g. the height of the entire population





# Probability Review II

# Probability Review

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- Structural properties
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# Joint Probability Distribution

- Random variables encodes attributes
- Not all possible combination of attributes are equally likely
  - Joint probability distributions quantify this
- $P(X = x, Y = y) = P(x, y)$ 
  - Generalizes to N-RVs
  - $\sum_x \sum_y P(X = x, Y = y) = 1$
  - $\int \int_{x y} f_{X,Y}(x, y) dx dy = 1$

# Chain Rule

- Always true

- $P(x, y, z) = p(x) p(y|x) p(z|x, y)$

$$= p(z) p(y|z) p(x|y, z)$$

$$= \dots p(y) p(x|y) p(z|x, y)$$

$$P(x, y) = p(x) \cdot p(y|x)$$

# Conditional Probability

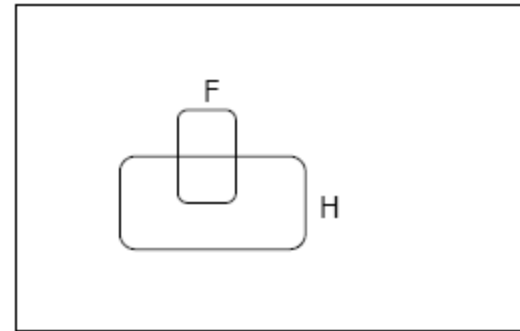
$$P(X = x | Y = y) = \frac{P(X = x \cap Y = y)}{P(Y = y)}$$

↓ F      ↓ H

events

But we will always write it this way:

$$P(x | y) = \frac{p(x, y)}{\underline{p(y)}}$$



$p(y)$

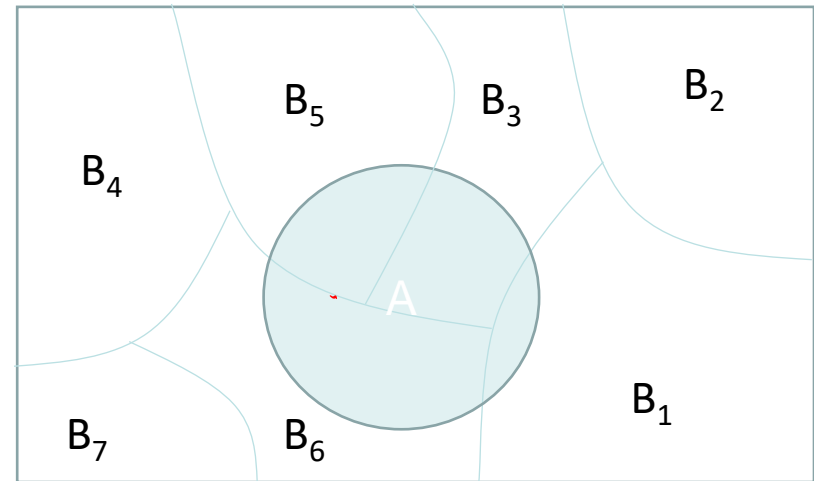
# Marginalization

$p(x)$

- We know  $p(X, Y)$ , what is  $P(X=x)$ ?
- We can use the law of total probability, why?

$P(x, Y)$

$$\begin{aligned} p(x) &= \sum_y P(x, y) \\ &= \sum_y P(y)P(x|y) \end{aligned}$$



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# Marginalization Cont.

- Another example

$$\begin{aligned} \underline{p(x)} &= \sum_{\underline{y,z}} P(x, y, z) \\ &= \sum_{\underline{z,y}} P(y, z) P(x | y, z) \end{aligned}$$

# Bayes Rule

⇒ AI

- We know that  $P(\text{rain}) = 0.5$ 
  - If we also know that the grass is wet, then how this affects our belief about whether it rains or not?

$$P(\text{rain} | \text{wet}) = \frac{P(\text{rain})P(\text{wet} | \text{rain})}{P(\text{wet})}$$

$$P(x | y) = \frac{P(x)P(y | x)}{P(y)}$$



# Bayes Rule cont.

- You can condition on more variables

$$P(x | \underline{y}, z) = \frac{P(x | z)P(y | x, z)}{P(y | z)}$$

Markov Chains

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# Independence

- X is independent of Y means that knowing Y does not change our belief about X.

- $P(X|Y=y) = P(X)$

- $P(X=x, Y=y) = P(X=x) \cdot P(Y=y)$

- The above should hold for all  $x, y$

- It is symmetric and written as  $X \perp Y$

$$X \perp Y$$

$$P(X=x, Y=y) = P(X=x) \cdot P(Y=y) \quad \forall x, y$$

$n=20$

# Independence

- $X_1, \dots, X_n$  are independent if and only if

$$P(X_1 \in A_1, \dots, X_n \in A_n) = \prod_{i=1}^n P(X_i \in A_i)$$

- If  $X_1, \dots, X_n$  are independent and identically distributed we say they are *iid* (or that they are a random sample) and we write

$$\underline{X_1}, \dots, \underline{X_n} \sim P$$

$$X \sim N(\mu, \sigma^2)$$

# CI: Conditional Independence

- RV are rarely independent but we can still leverage local structural properties like Conditional Independence.
- $X \perp Y \mid Z$  if once  $Z$  is observed, knowing the value of  $Y$  does not change our belief about  $X$ 
  - $P(\text{rain} \perp \text{sprinkler's on} \mid \text{cloudy})$
  - $P(\text{rain} \not\perp \text{sprinkler's on} \mid \text{wet grass})$

# Conditional Independence

- $P(X=x \mid Z=z, Y=y) = P(X=x \mid Z=z)$
- $P(Y=y \mid Z=z, X=x) = P(Y=y \mid Z=z)$
- $P(X=x, Y=y \mid Z=z) = P(X=x \mid Z=z) P(Y=y \mid Z=z)$

We call these factors : very useful concept !!

$$P(x \mid z, y) = P(x \mid z)$$
$$P(y \mid z, x) = P(y \mid z)$$

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$$g(X) = aX$$

# Mean and Variance

- Mean (Expectation):  $\mu = E(X)$ 
  - Discrete RVs:  $E(X) = \sum_{v_i} v_i P(X = v_i)$   
 $\Rightarrow E(g(X)) = \sum_{v_i} g(v_i) P(X = v_i)$

- Continuous RVs:

$$E(X) = \int_{-\infty}^{+\infty} xf(x) dx$$

$$E(g(X)) = \int_{-\infty}^{+\infty} g(x)f(x) dx$$

$$E[X]$$

$$\Rightarrow \begin{array}{l} 1 \cdot \frac{1}{3} \\ 2 \cdot \frac{1}{3} \\ 3 \cdot \frac{1}{3} \end{array}$$

$$\frac{1}{3} + \frac{2}{3} + \frac{3}{3} = 2$$

$$E[g(X)]$$



$$E(X+Y) = E(X) + E(Y)$$

## Mean and Variance

$$E[aX] = a E[X] \quad E[(X-\mu)^2]$$

- Variance:  $\text{Var}(X) = E((X-\mu)^2)$

$$\text{Var}(X) = E(X^2) - \mu^2$$

- Discrete RVs:  $V(X) = \sum_{v_i} (v_i - \mu)^2 P(X = v_i)$

- Continuous RVs:  $V(X) = \int_{-\infty}^{+\infty} (x - \mu)^2 f(x) dx$

- Covariance:  $E(x^2) - 2\mu E(X) + \mu^2$

$$\text{Cov}(X, Y) = E((X - \mu_x)(Y - \mu_y)) = E(XY) - \mu_x \mu_y$$

# Mean and Variance

- Correlation:

$$\rho(X, Y) = \text{Cov}(X, Y) / \sigma_x \sigma_y$$

$$\underline{-1} \leq \rho(X, Y) \leq \underline{1}$$

# Properties

- Mean

- $E(X+Y) = E(X) + E(Y)$

- $E(aX) = aE(X)$

- If X and Y are independent,  $E(XY) = E(X) \cdot E(Y)$

$X, Y$  independent

- Variance

- $V(aX+b) = a^2V(X)$

- If X and Y are independent,  $V(X+Y) = V(X) + V(Y)$

0 → MSJ

# Some more properties

- The conditional expectation of  $Y$  given  $X$  when the value of  $X = x$  is:

$$\underline{E(Y | X = x)} = \int \underline{y^*} p(y | x) dy \rightarrow$$

- The Law of Total Expectation or Law of Iterated Expectation:

$$\underline{E(Y)} = E[\underline{E(Y | X)}] = \int \underline{E(Y | X = x)} \underline{p_X(x)} dx$$

$\downarrow$   
 $= X$

# Some more properties

- The law of Total Variance:

$$\underline{\text{Var}(Y)} = \underline{\text{Var}[E(Y | X)]} + \underline{E[\text{Var}(Y | X)]}$$

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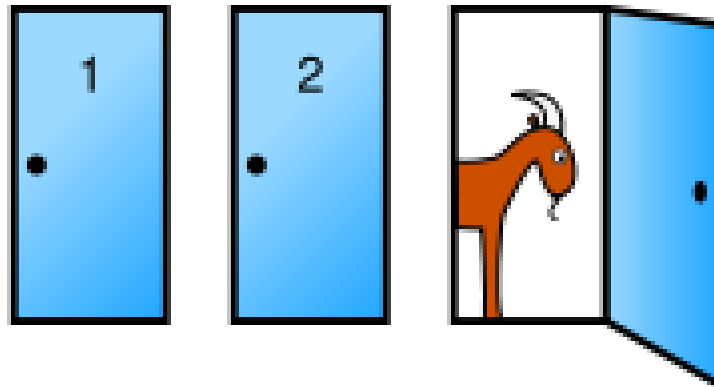
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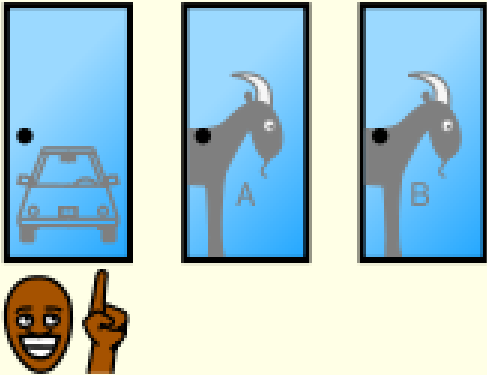
# Probability Review III



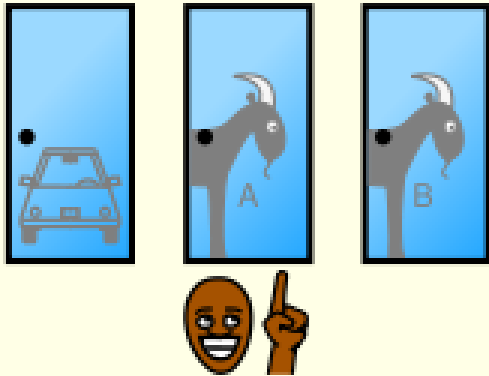
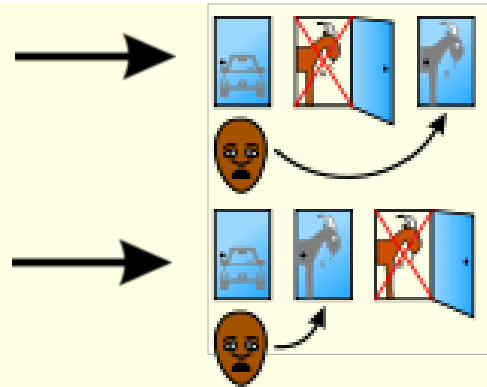
# Monty Hall Problem

- You're given the choice of three doors: Behind one door is a car; behind the others, goats.
- You pick a door, say No. 1
- The host, who knows what's behind the doors, opens another door, say No. 3, which has a goat.
- Do you want to pick door No. 2 instead?

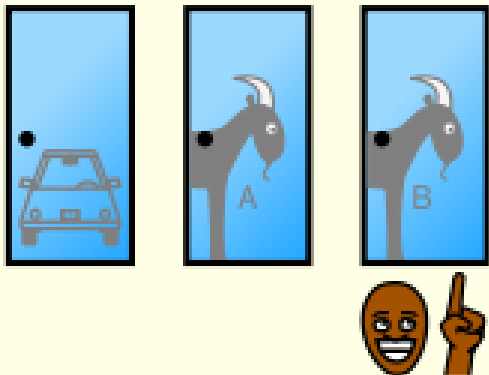
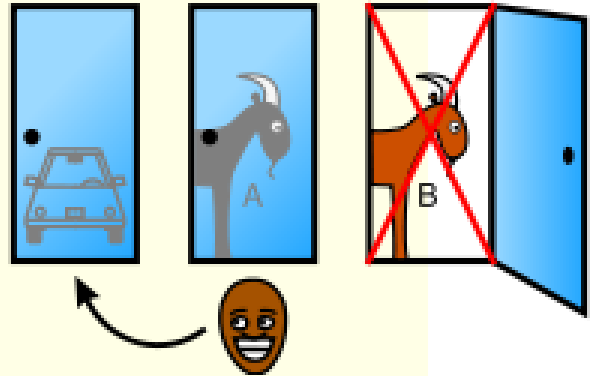




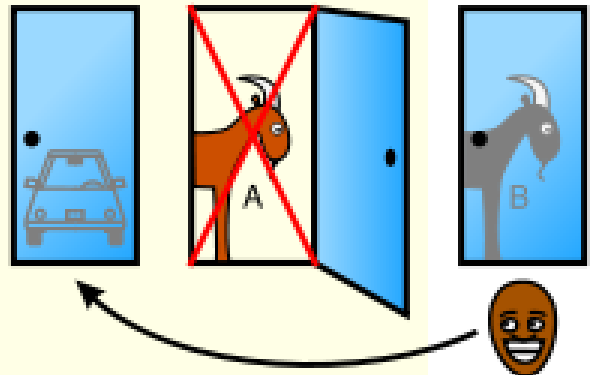
*Host reveals  
Goat A  
or  
Host reveals  
Goat B*



*Host must  
reveal Goat B*



*Host must  
reveal Goat A*



# Monty Hall Problem: Bayes Rule

- $C_i$  : the car is behind door  $i$ ,  $i = 1, 2, 3$
- $P(C_i) = 1/3$
- $H_{ij}$  : the host opens door  $j$  after you pick door  $i$

- $$P(H_{ij} | C_k) = \begin{cases} 0 & i = j \\ 0 & j = k \\ 1/2 & i = k \\ 1 & i \neq k, j \neq k \end{cases}$$

# Monty Hall Problem: Bayes Rule cont.

- Without loss of generality,  $i=1, j=3$

- $$P(C_1 | H_{13}) = \frac{P(H_{13} | C_1) P(C_1)}{P(H_{13})}$$

- $$P(H_{13} | C_1) P(C_1) = \frac{1}{2} \cdot \frac{1}{3} = \frac{1}{6}$$

# Monty Hall Problem: Bayes Rule cont.

- $$\begin{aligned} P(H_{13}) &= P(H_{13}, C_1) + P(H_{13}, C_2) + P(H_{13}, C_3) \\ &= P(H_{13} | C_1)P(C_1) + P(H_{13} | C_2)P(C_2) \\ &= \frac{1}{6} + 1 \cdot \frac{1}{3} \\ &= \frac{1}{2} \end{aligned}$$
- $$P(C_1 | H_{13}) = \frac{1/6}{1/2} = \frac{1}{3}$$

# Monty Hall Problem: Bayes Rule cont.

- $P(C_1 | H_{13}) = \frac{1/6}{1/2} = \frac{1}{3}$
- $P(C_2 | H_{13}) = 1 - \frac{1}{3} = \frac{2}{3} > P(C_1 | H_{13})$
- *You should switch!*

# Acknowledgment

- Carlos Guestrin recitation slides:  
[http://www.cs.cmu.edu/~guestrin/Class/10708/recitations/r1/Probability\\_and\\_Statistics\\_Review.ppt](http://www.cs.cmu.edu/~guestrin/Class/10708/recitations/r1/Probability_and_Statistics_Review.ppt)
- Andrew Moore Tutorial:  
<http://www.autonlab.org/tutorials/prob.html>
- Monty hall problem:  
[http://en.wikipedia.org/wiki/Monty\\_Hall\\_problem](http://en.wikipedia.org/wiki/Monty_Hall_problem)
- [http://www.cs.cmu.edu/~guestrin/Class/10701-F07/recitation\\_schedule.html](http://www.cs.cmu.edu/~guestrin/Class/10701-F07/recitation_schedule.html)
- Chi-square test for independence  
<http://stattrek.com/chi-square-test/independence.aspx>

# Introduction to Randomized Algorithms



# Outline

- Preliminaries and Motivation
- Analysis of
  - Randomized Quick Sort
  - Karger's Min-cut Algorithm
- Basic Analytical Tools

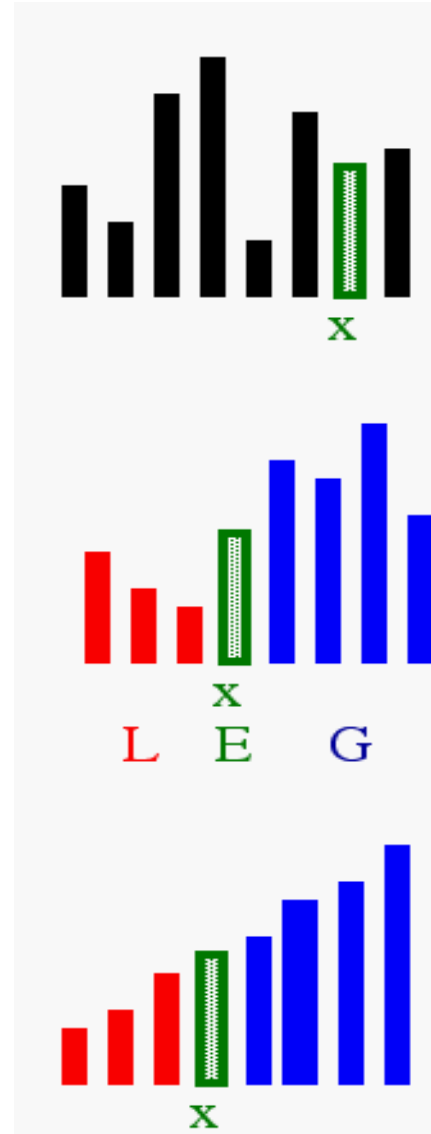
# Preliminaries and Motivation

# Quick Sort

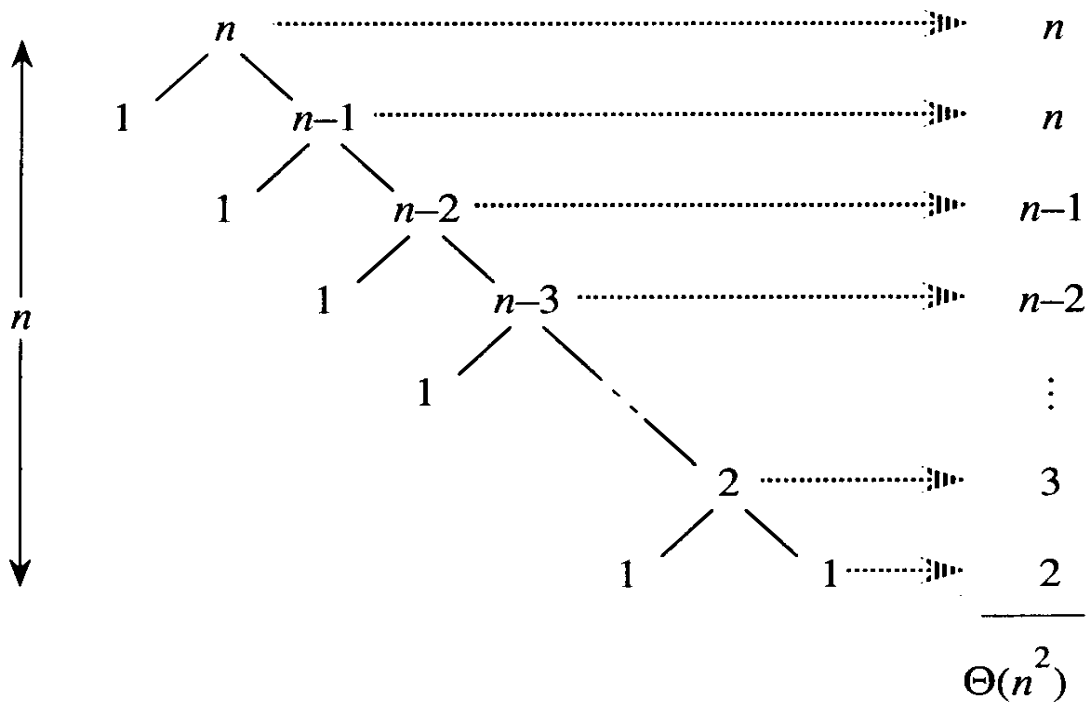
**Select:** pick an arbitrary element  $x$  in  $S$  to be the pivot.

**Partition:** rearrange elements so that elements with value less than  $x$  go to List  $L$  to the left of  $x$  and elements with value greater than  $x$  go to the List  $R$  to the right of  $x$ .

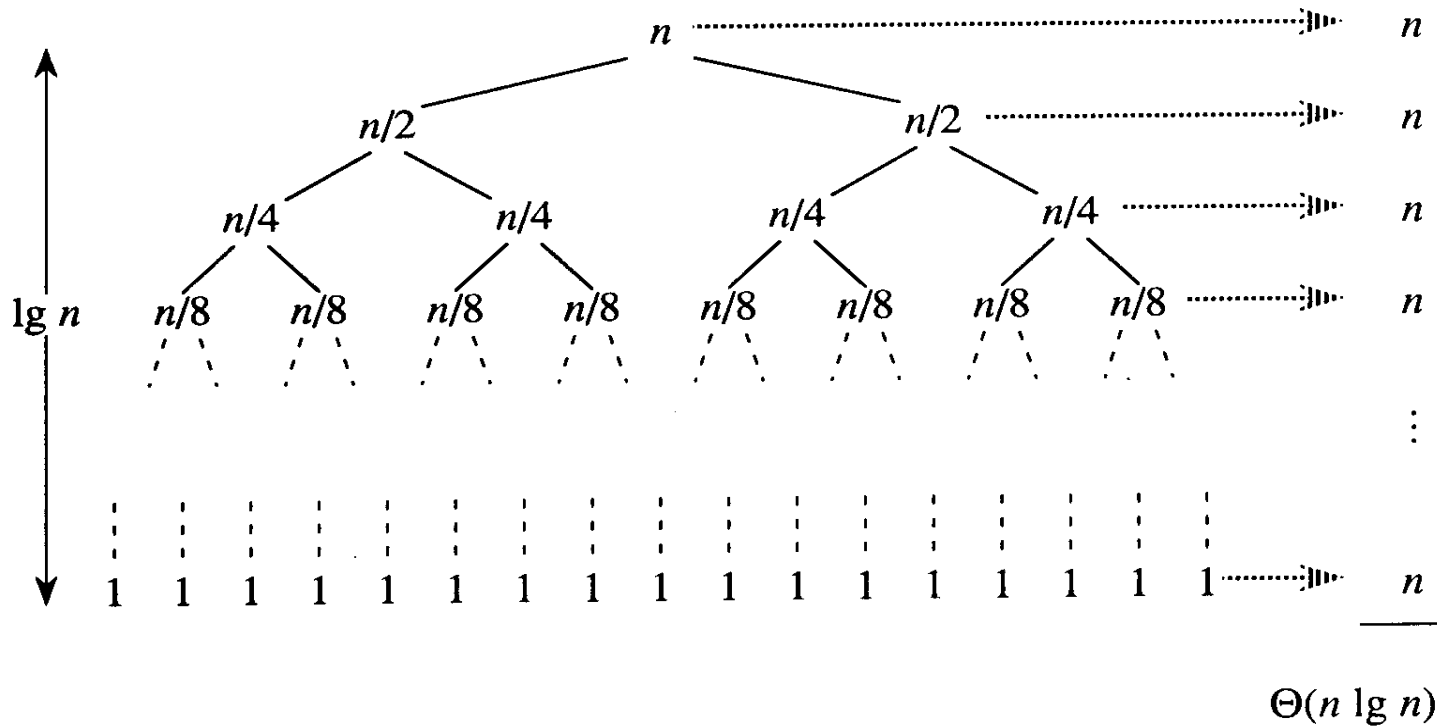
**Recursion:** recursively sort the lists  $L$  and  $R$ .



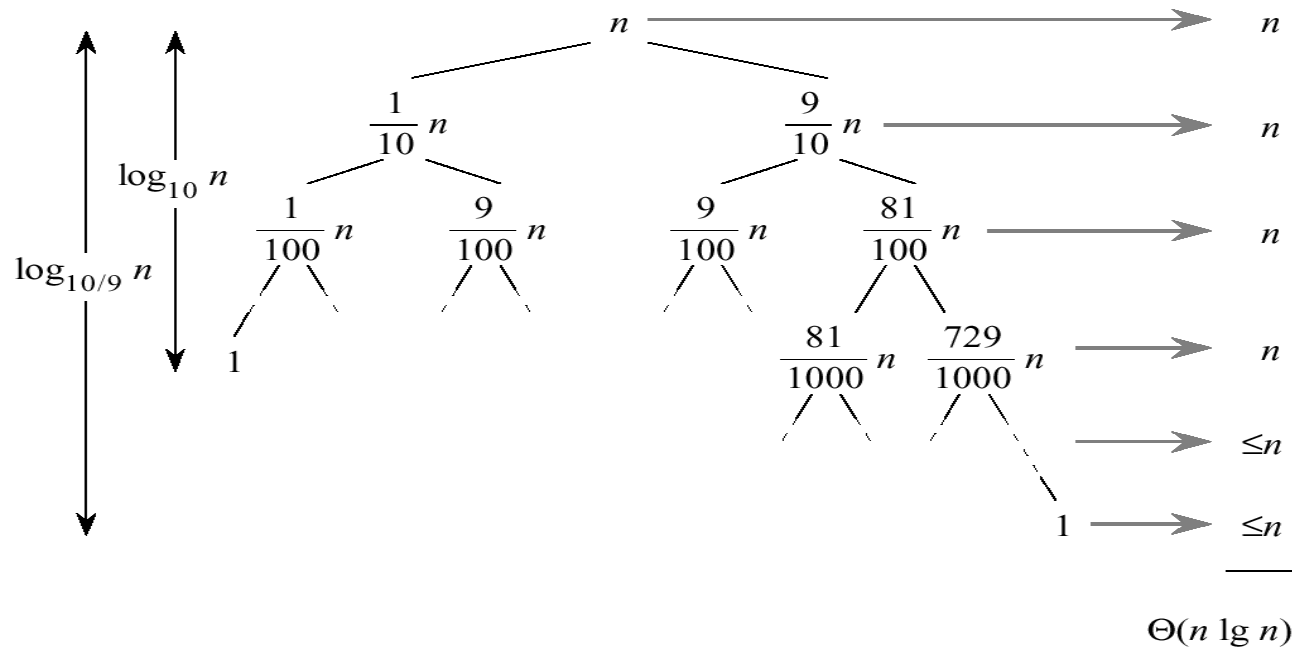
# Worst Case Partitioning of Quick Sort



# Best Case Partitioning of Quick Sort



# Average Case of Quick Sort



# Randomized Quick Sort

## Randomized-Partition( $A, p, r$ )

1.  $i \leftarrow \text{Random}(p, r)$
2. exchange  $A[r] \leftrightarrow A[i]$
3. return **Partition**( $A, p, r$ )

## Randomized-Quicksort( $A, p, r$ )

1. if  $p < r$
2.    **then**  $q \leftarrow \text{Randomized-Partition}(A, p, r)$
3.        **Randomized-Quicksort**( $A, p, q-1$ )
4.        **Randomized-Quicksort**( $A, q+1, r$ )

# Randomized Quick Sort

- Exchange  $A[r]$  with an element chosen at random from  $A[p\dots r]$  in **Partition**.
- The pivot element is equally likely to be any of input elements.
- *For any given input, the behavior of Randomized Quick Sort is determined not only by the input but also by the random choices of the pivot.*
- We add randomization to Quick Sort to obtain for any input the expected performance of the algorithm to be good.

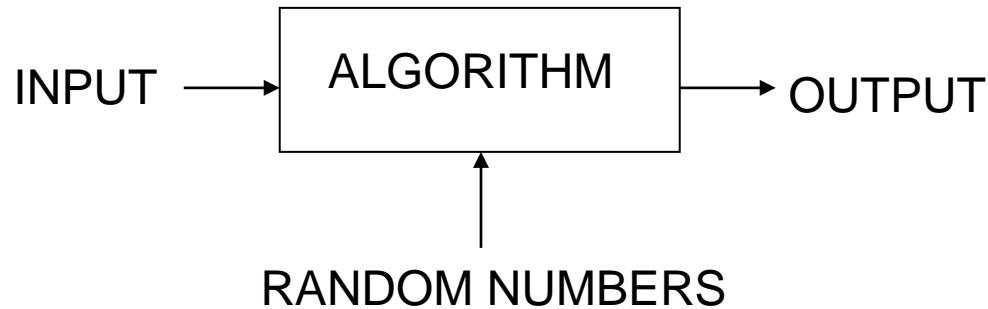


# Deterministic Algorithms



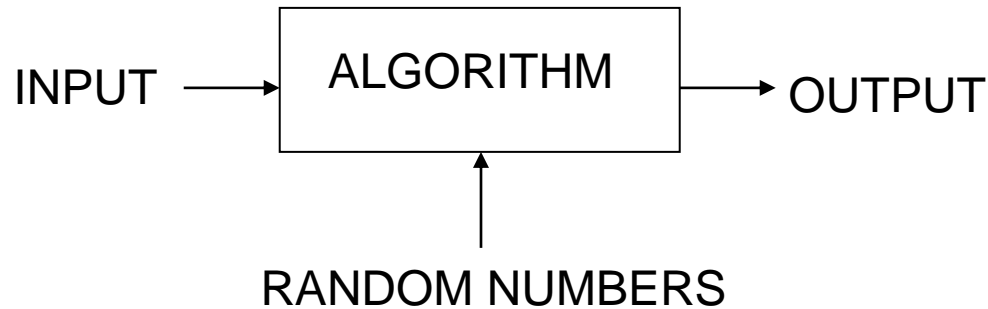
**Goal:** Prove for all input instances the algorithm solves the problem correctly and the number of steps is bounded by a polynomial in the size of the input.

# Randomized Algorithms



- In addition to input, algorithm takes a source of random numbers and makes random choices during execution;
- Behavior can vary even on a fixed input;

# Las Vegas Randomized Algorithms



**Goal:** Prove that for all input instances the algorithm solves the problem correctly and the expected number of steps is bounded by a polynomial in the input size.

**Note:** The expectation is over the random choices made by the algorithm.

# Probabilistic Analysis of Algorithms

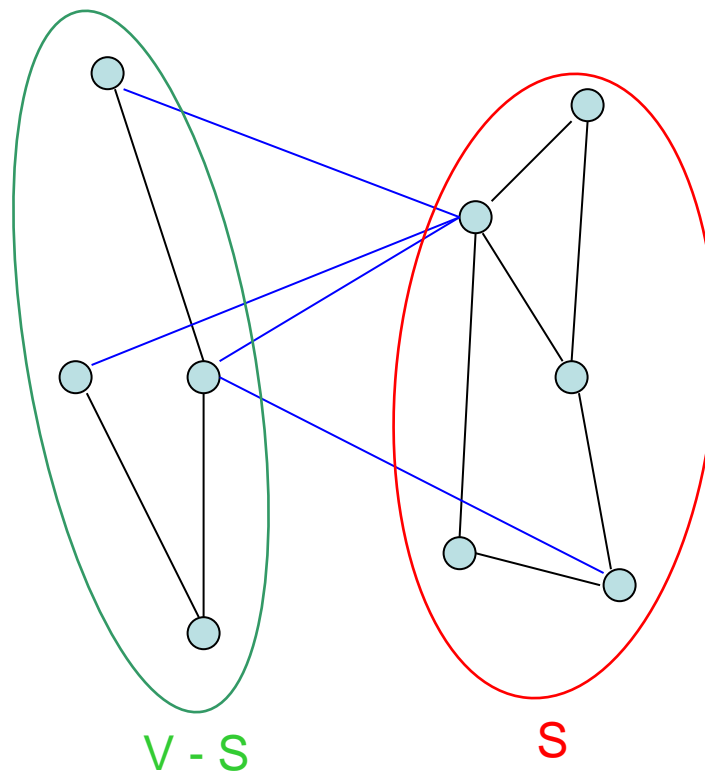


Input is assumed to be from a probability distribution.

**Goal:** Show that for all inputs the algorithm works correctly and for most inputs the number of steps is bounded by a polynomial in the size of the input.

# Min-cut for Undirected Graphs

Given an undirected graph, a global min-cut is a cut  $(S, V-S)$  minimizing the number of crossing edges, where a crossing edge is an edge  $(u,v)$  s.t.  $u \in S$  and  $v \in V-S$ .

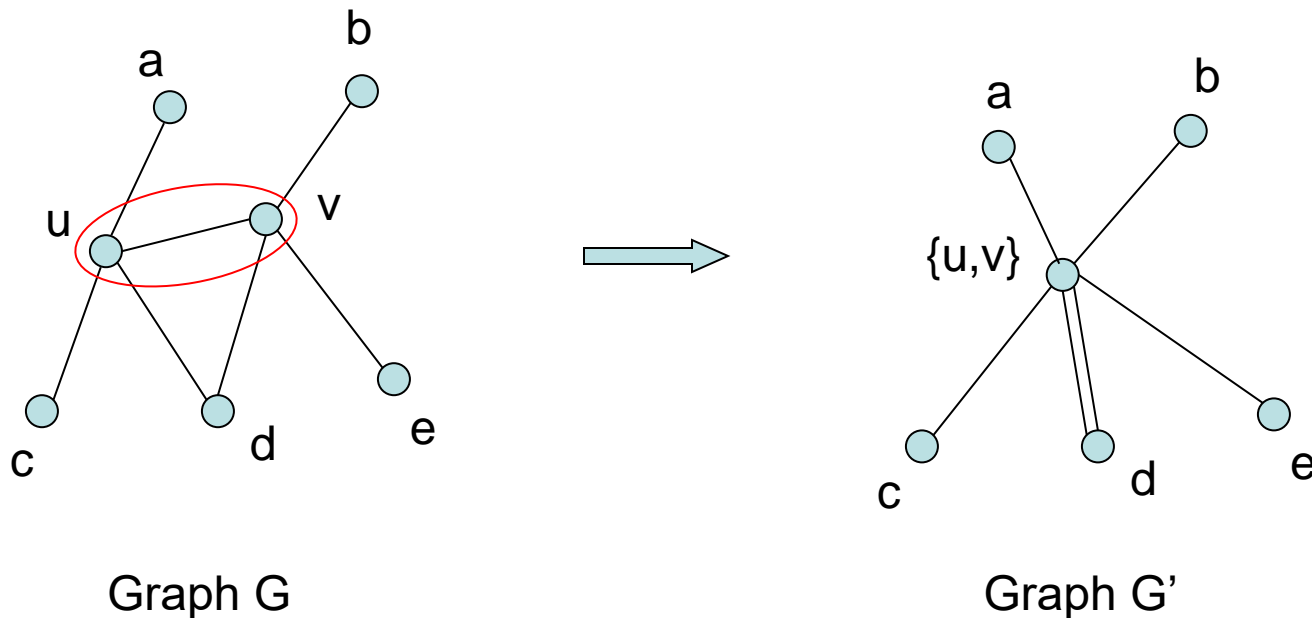


# Graph Contraction

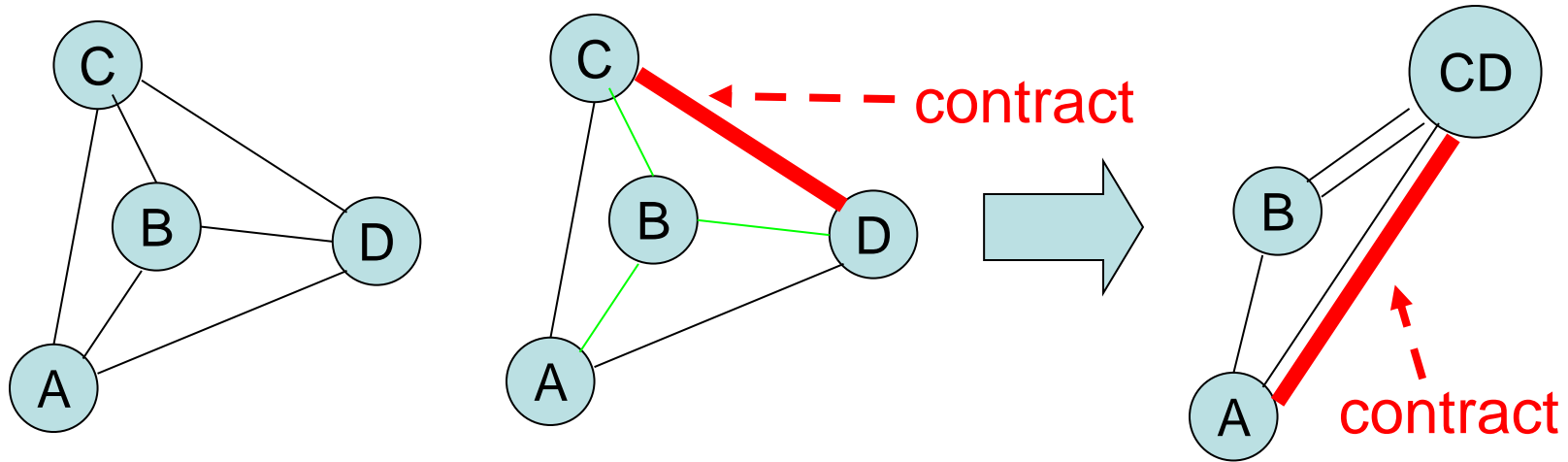
For an undirected graph  $G$ , we can construct a new graph  $G'$  by contracting two vertices  $u, v$  in  $G$  as follows:

- $u$  and  $v$  become one vertex  $\{u,v\}$  and the edge  $(u,v)$  is removed;
- the other edges incident to  $u$  or  $v$  in  $G$  are now incident on the new vertex  $\{u,v\}$  in  $G'$ ;

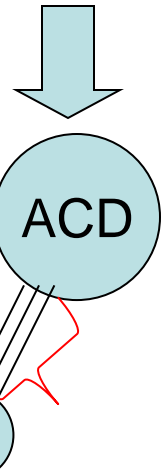
Note: There may be multi-edges between two vertices. We just keep them.



# Karger's Min-cut Algorithm



(i) Graph G    (ii) Contract nodes C and D    (iii) contract nodes A and CD



**Note:** C is a cut but not necessarily a min-cut.

(iv) Cut  $C = \{(A,B), (B,C), (B,D)\}$

# Karger's Min-cut Algorithm

For  $i = 1$  to  $100n^2$   
  repeat  
    randomly pick an edge  $(u,v)$   
    contract  $u$  and  $v$   
  until two vertices are left  
   $c_i \leftarrow$  the number of edges between them  
Output mini  $c_i$



# Key Idea

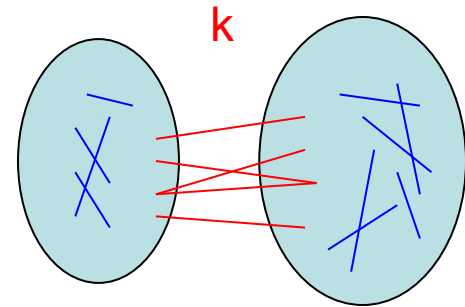
- Let  $C^* = \{c_1^*, c_2^*, \dots, c_k^*\}$  be a min-cut in  $G$  and  $C^i$  be a cut determined by Karger's algorithm during some iteration  $i$ .
- $C^i$  will be a min-cut for  $G$  if during iteration "i" none of the edges in  $C^*$  are contracted.
- If we can show that with prob.  $\Omega(1/n^2)$ , where  $n = |V|$ ,  $C^i$  will be a min-cut, then by repeatedly obtaining min-cuts  $O(n^2)$  times and taking minimum gives the min-cut with high prob.

# Analysis of Karger's Min-Cut Algorithm

# Analysis of Karger's Algorithm

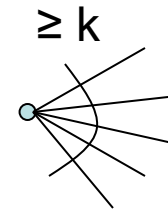
Let  $k$  be the number of edges of min cut  $(S, V-S)$ .

If we never picked a crossing edge in the algorithm, then the number of edges between two last vertices is the correct answer.



The probability that in step 1 of an iteration a crossing edge is not picked =  $(|E|-k)/|E|$ .

By def of min cut, we know that each vertex  $v$  has degree at least  $k$ , Otherwise the cut  $(\{v\}, V-\{v\})$  is lighter.



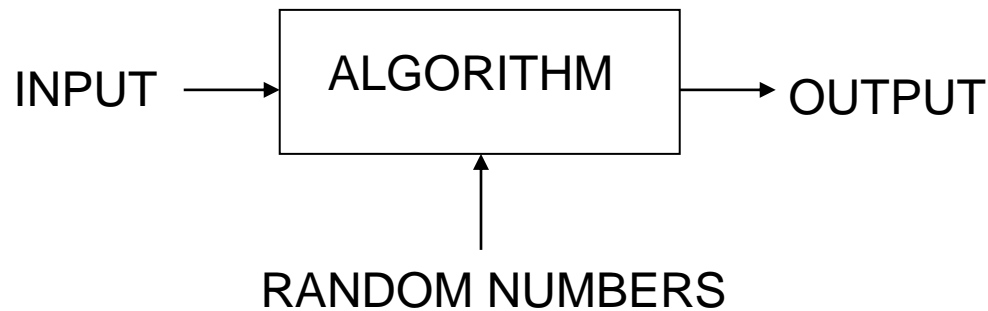
Thus  $|E| \geq nk/2$  and  $(|E|-k)/|E| = 1 - k/|E| \geq 1-2/n$ .

# Analysis of Karger's Algorithm

- In step 1,  $\Pr$  [no crossing edge picked]  $\geq 1 - 2/n$
- Similarly, in step 2,  $\Pr$  [no crossing edge picked]  $\geq 1 - 2/(n-1)$
- In general, in step  $j$ ,  $\Pr$  [no crossing edge picked]  $\geq 1 - 2/(n-j+1)$
- $\Pr$  {the  $n-2$  contractions never contract a crossing edge}
  - =  $\Pr$  [first step good]
    - \*  $\Pr$  [second step good after surviving first step]
    - \*  $\Pr$  [third step good after surviving first two steps]
    - \* ...
    - \*  $\Pr$  [( $n-2$ )-th step good after surviving first  $n-3$  steps]  
 $\geq (1 - 2/n) (1 - 2/(n-1)) \dots (1 - 2/3)$   
 $= [(n-2)/n] [(n-3)(n-1)] \dots [1/3] = 2/[n(n-1)] = \Omega(1/n^2)$

# Introduction to Randomized Algorithms: Monte Carlo Randomized Algorithm

# Monte Carlo Randomized Algorithms



**Goal:** Prove that the algorithm

- with high probability solves the problem correctly;
- for every input the expected number of steps is bounded by a polynomial in the input size.

**Note:** The expectation is over the random choices made by the algorithm.

# Monte Carlo versus Las Vegas

- A Monte Carlo algorithm runs produces an answer that is correct with non-zero probability, whereas a Las Vegas algorithm always produces the correct answer.
- The running time of both types of randomized algorithms is a random variable whose expectation is bounded say by a polynomial in terms of input size.
- These expectations are only over the random choices made by the algorithm independent of the input. Thus independent repetitions of Monte Carlo algorithms drive down the failure probability exponentially.

# Motivation for Randomized Algorithms

- Simplicity;
- Performance;
- Reflects reality better (Online Algorithms);
- For many hard problems helps obtain better complexity bounds when compared to deterministic approaches;



# Analysis of Randomized Quick Sort

# Linearity of Expectation

If  $X_1, X_2, \dots, X_n$  are random variables, then

$$E \left[ \sum_{i=1}^n X_i \right] = \sum_{i=1}^n E[X_i]$$

# Notation

$z_2$	$z_9$	$z_8$	$z_3$	$z_5$	$z_4$	$z_1$	$z_6$	$z_{10}$	$z_7$
2	9	8	3	5	4	1	6	10	7

- Rename the elements of  $A$  as  $z_1, z_2, \dots, z_n$ , with  $z_i$  being the  $i^{\text{th}}$  smallest element (Rank “ $i$ ”).
- Define the set  $Z_{ij} = \{z_i, z_{i+1}, \dots, z_j\}$  be the set of elements between  $z_i$  and  $z_j$ , inclusive.

# Expected Number of Total Comparisons in PARTITION

Let  $X_{ij} = I \{z_i \text{ is compared to } z_j\}$  ← indicator random variable

Let  $X$  be the total number of comparisons performed by the algorithm. Then

$$\left[ X = \sum_{i=1}^{n-1} \sum_{j=i+1}^n X_{ij} \right]$$

The expected number of comparisons performed by the algorithm is

$$E[X] = E \left[ \sum_{i=1}^{n-1} \sum_{j=i+1}^n X_{ij} \right] = \sum_{i=1}^{n-1} \sum_{j=i+1}^n E[X_{ij}]$$

by linearity  
of expectation

$$= \sum_{i=1}^{n-1} \sum_{j=i+1}^n \Pr\{z_i \text{ is compared to } z_j\}$$

# Comparisons in PARTITION

Observation 1: Each pair of elements is compared **at most once** during the entire execution of the algorithm

- Elements are compared only to the pivot point!
- Pivot point is excluded from future calls to PARTITION

Observation 2: Only the pivot is compared with elements in both partitions

$z_2$	$z_9$	$z_8$	$z_3$	$z_5$	$z_4$	$z_1$	$z_6$	$z_{10}$	$z_7$
2	9	8	3	5	4	1	6	10	7

$Z_{1,6} = \{1, 2, 3, 4, 5, 6\}$

$\{7\}$   
pivot

$Z_{8,9} = \{8, 9, 10\}$

Elements between different partitions are never compared

# Comparisons in PARTITION

$z_2$	$z_9$	$z_8$	$z_3$	$z_5$	$z_4$	$z_1$	$z_6$	$z_{10}$	$z_7$
2	9	8	3	5	4	1	6	10	7

$Z_{1,6} = \{1, 2, 3, 4, 5, 6\}$

$\{7\}$

$Z_{8,9} = \{8, 9, 10\}$

$\Pr\{z_i \text{ is compared to } z_j\}?$

Case 1: pivot chosen such as:  $z_i < x < z_j$

- $z_i$  and  $z_j$  will never be compared

Case 2:  $z_i$  or  $z_j$  is the pivot

- $z_i$  and  $z_j$  will be compared
- only if one of them is chosen as pivot before any other element in range  $z_i$  to  $z_j$

# Expected Number of Comparisons in PARTITION

$\Pr\{Z_i \text{ is compared with } Z_j\}$

$= \Pr\{Z_i \text{ or } Z_j \text{ is chosen as pivot before other elements in } Z_{i,j}\} = 2 / (j-i+1)$

$$E[X] = \sum_{i=1}^{n-1} \sum_{j=i+1}^n \Pr\{z_i \text{ is compared to } z_j\}$$

$$E[X] = \sum_{i=1}^{n-1} \sum_{j=i+1}^n \frac{2}{j-i+1} = \sum_{i=1}^{n-1} \sum_{k=1}^{n-i} \frac{2}{k+1} < \sum_{i=1}^{n-1} \sum_{k=1}^n \frac{2}{k} = \sum_{i=1}^{n-1} O(\lg n)$$

$$= O(n \lg n)$$

# Basic Analytical Tools



# Tail Bounds

- In the analysis of randomized algorithms, we need to know how much does an algorithms run-time/cost deviate from its expected run-time/cost.
- That is we need to find an upper bound on  $\Pr[X \text{ deviates from } E[X] \text{ a lot}]$ . This we refer to as the tail bound on  $X$ .

# Markov and Chebyshev's Inequality

**Markov's Inequality** If  $X \geq 0$ , then

$$\Pr[X \geq a] \leq E[X]/a.$$

**Proof.** Suppose  $\Pr[X \geq a] > E[X]/a$ . Then

$$E[X] \geq a \cdot \Pr[X \geq a] > a \cdot E[X]/a = E[X].$$

**Chebyshev's Inequality:**  $\Pr[|X-E[X]| \geq a] \leq \text{Var}[X] / a^2$ .

**Proof.**

$$\begin{aligned} & \Pr[|X-E[X]| \geq a] \\ &= \Pr[|X-E[X]|^2 \geq a^2] \\ &= \Pr[(X-E[X])^2 \geq a^2] \\ &\leq E[(X-E[X])^2] / a^2 \quad // \text{Markov on } (X-E[X])^2 \\ &= \text{Var}[X] / a^2 \end{aligned}$$